

Simulating and Mitigating the Atmospheric Effects for CMB ground-based Observations

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Presentation overview

CMB-S4
Summer
Meeting

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Scientific
framework

Systematic
effects

Reliable
simulation of
the
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contribution

Mitigation
Techniques

Conclusions
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- 1 Scientific framework
- 2 Systematic effects
- 3 Reliable simulation of the atmospheric contribution
- 4 Mitigation Techniques
- 5 Conclusions and future perspectives

Introduction

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CMB observation approaches

- Satellite mission
- Balloon-Based telescope
- Ground-Based telescope

Analysis approach

- **The B-modes detection:** limited by the control of the systematic effects
 - Requires to use a **sinergistic approach** between all of these philosophies
- The systematic contributions has to be **characterized** and **modeled** as better as we can.

Systematic Effects

The atmosphere

The atmospheric spurious contribution

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The atmospheric load represents the **main contribution** of noise for CMB ground-based telescope.

- We have considered the atmospheric emission **unpolarized**.
- The main contribution (if we exclude the O_2 Zeeman's emission) is due to the **instrumental leakage** from I to P channel.
- In this context, the atmospheric pattern that we can find in the I channel, is the **same** that is present in the **P channel** (with a rescale factor due to the leakage parameter, 1% for LSPE/Strip Q-band focalplane).
- I have studied the atmospheric effects in temperature, and I created an adaptive mapmaker to mitigate its fluctuations.

LSPE Experiment

The main features of the LSPE experiment¹

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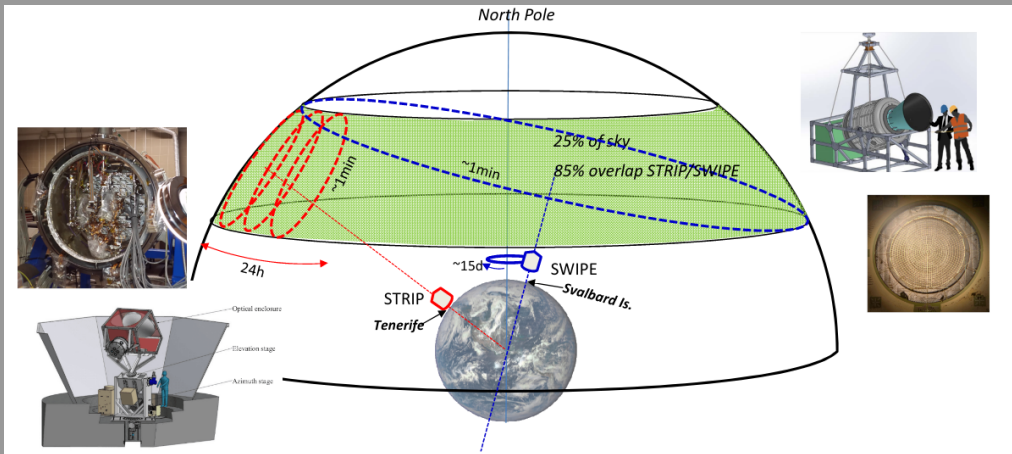
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¹10.1088/1475-7516/2021/08/008 JCAP

The Atmospheric Statistical Picture

The white noise estimation

Collect the wheater history of the site

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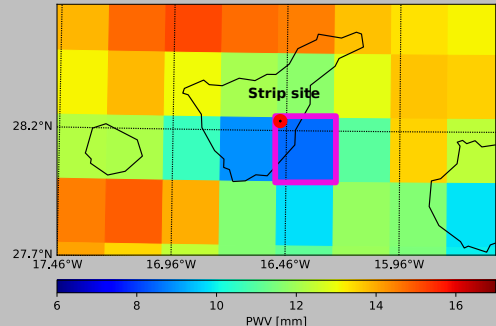
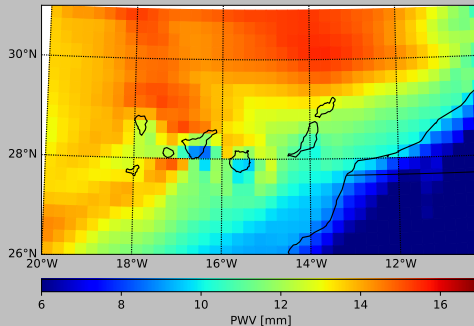
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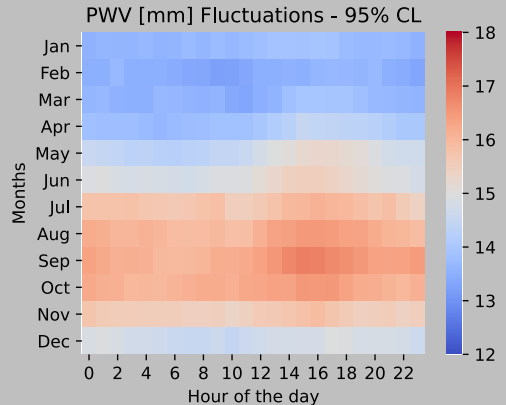
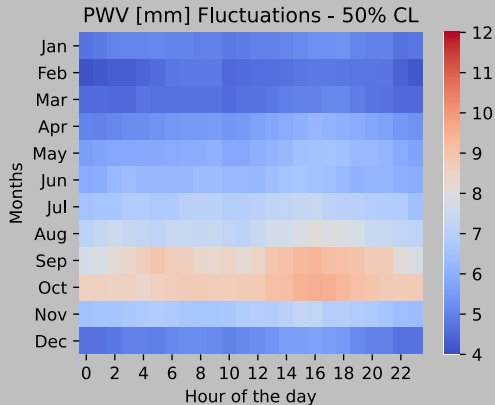
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ERA-5 graphical representation



White noise seasonal fluctuations

White noise



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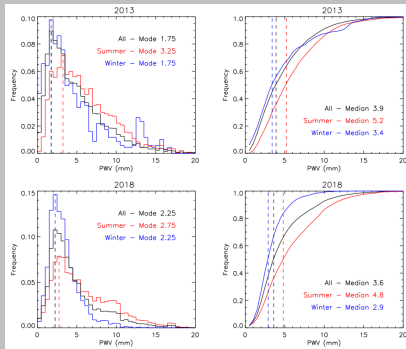
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The actual atmospheric quality from Teide Observatory

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PWV Observed by QUIJOTE



- Median PWV = 3.7mm
- During the good weather condition (the 20% of the observations) the PWV was below 2mm.
- **We have to find a way to correct/calibrate the ERA-5 data**

Comparison with QUIJOTE MFI

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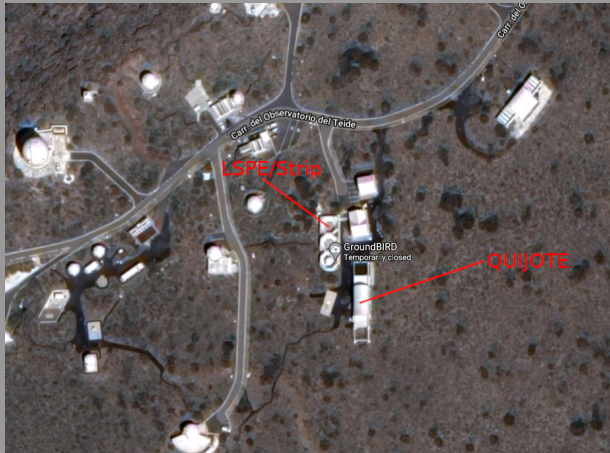
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The QUIJOTE telescope is located at Observatorio del Teide (2400 m), near the LSPE/Strip site. We can share data about

- **Instrumental systematics**
- **Atmospheric fluctuations.**

The site location represent a great opportunity to approach a joint data analysis

Comparison with QUIJOTE MFI

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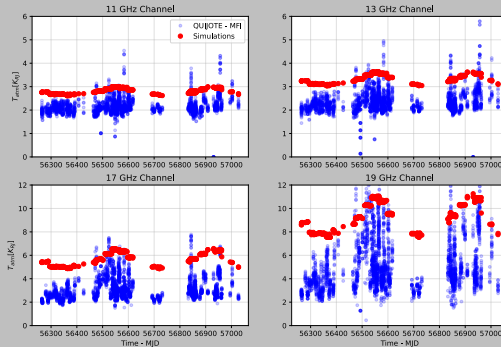
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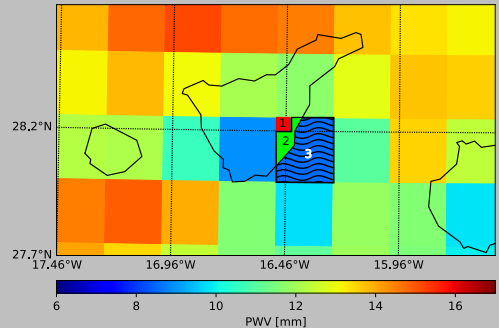
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Simulations and measurements



Contribute of the ocean



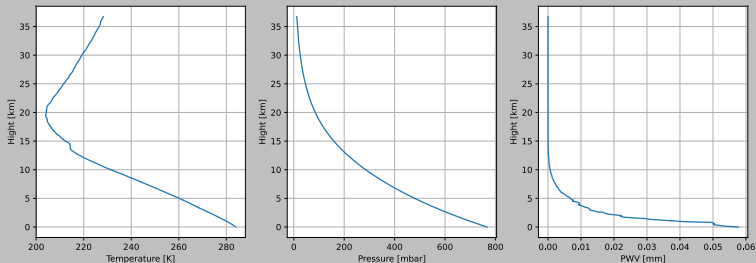
Balloon measurements

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To mitigate the spatial resolution issue, we used the atmospheric profiles measured from Izaña by balloon probes

Profiles

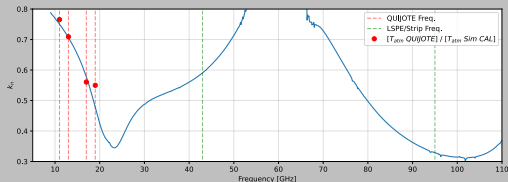


- Point like spatial resolution
- Poor temporal resolution
- Annual median profiles

Pixel calibration

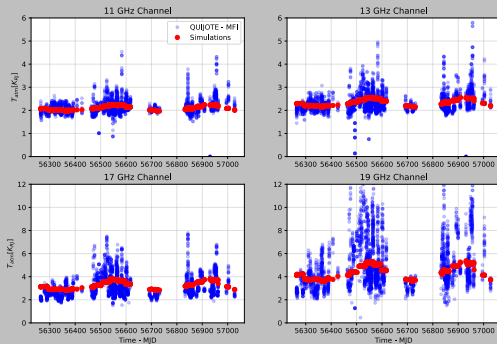
Using CAL² and AM we have estimated the contribute of the ocean.

Correction factor



- **Blue line:** represents k_ν evaluated with simulated T_{atm}
- **Red points:** k_ν out of QUIJOTE measurements and CAL simulation

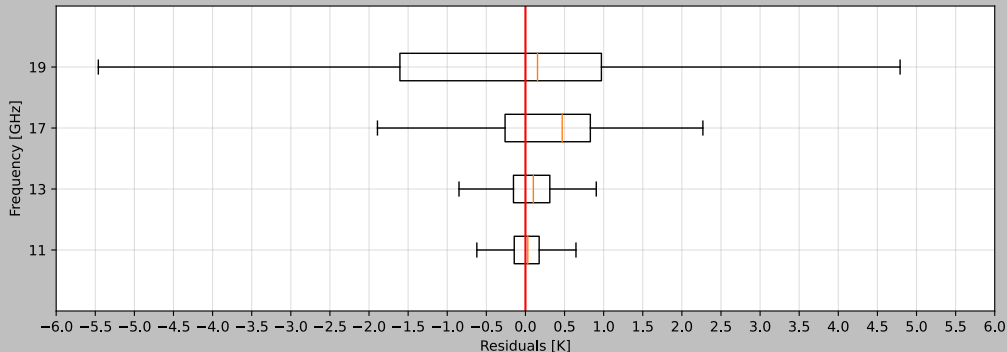
Comparison with the data



²doi.org/10.5281/zenodo.4597960

Simulations and data compatibility level

(Observed - Simulated) residuals



The boxplots are compatible to zero within 1σ

The Atmospheric Statistical Picture

Atmospheric correlations

The atmospheric correlations

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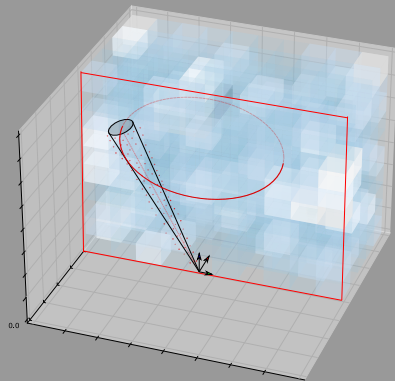
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Kolmogorov Power Spectrum

- The atm emission: is due by O_2 and H_2O
- The O_2 molecules are well mixed in the atmosphere
- The H_2O create turbulent structures (described by Kolmogorov)
- The features of this noise are difficult to characterized
 - The atmospheric conditions show different levels of fluctuations in time
 - These fluctuations are "convolved" with telescope scanning strategy



Binned maps

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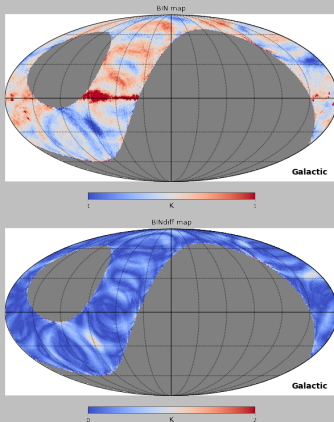
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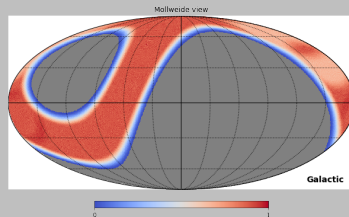
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January



Hit map



The scan velocity is modulated as a function of the AZ angle

- **Hit homogeneously distributed**
- **Increase the number of cross-links**

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- Let's start from the well know MM equation $P^t N^{-2} P m = P^t N^{-2} d$
- In the case of instrumental noise a good representation of the noise covariance matrix N^{-2} is represented by the noise model $n = \sigma^2 [1 + f_{knee}/f]^\alpha$, where the CX corr. are considered very small / negligible
- This is not true for atmospheric noise. The CX corr between detectors is dominant.

Noise model

We can complete the noise model with the atmospheric correlations

- $$n(f) = \sigma^2 [1 + f_{knee}/f]^\alpha + N(w) \exp \left[-\frac{f^2}{2 * c(w)} \right]$$

where $N(w)$ and $c(w)$ depend on the weather parameters w , in particular PWV , T_s , P_s . The $c(w)$ parameter depends on $1/L_0$. The parameters $N(w)$ and $c(w)$ are updated every hour.

Mitigation Technique

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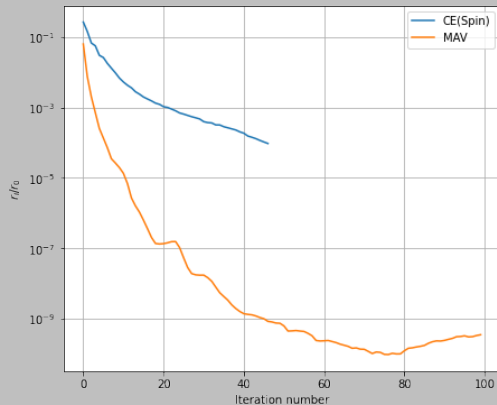
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To improve the atmospheric mitigation we can modify...

- Scanning strategy
 - CES at different speed $v(Az)$
 - Elevation modulation

In this way, the hits on the map are more uniform distributed. The increasing of the cross-links number improve the convergence speed-up of the conjugate gradient algorithm

Residuals



Denoised results

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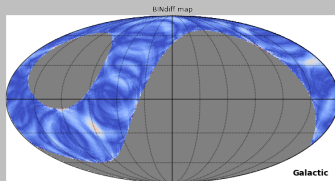
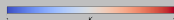
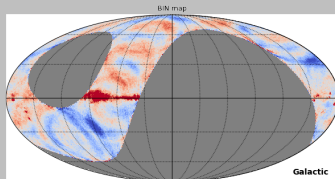
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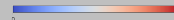
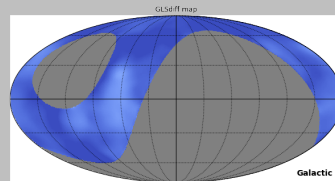
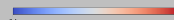
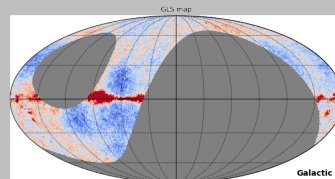
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January - binned map



Denoised map



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- Complete the mapmaker algorithm
 - Now the code is slow, in particular the part fast fourier transform part.
 - Now, it is written in Rust, but has to be converted in Julia (the language of the Strip simulation framework (by Maurizio Tomasi))
 -
- Create the polarization maps (Q and U)
 - Use the $I \rightarrow Q$ and $I \rightarrow U$ data to create polarization maps with atmospheric effects
 -
- Create the polarization map of the whole experiment duty cycle (1 year of observations)
 - Improve the efficiency of the mapmaker working on the speed-up of the fft part

Thank you for this great experience!